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(71) Applicant (for all designated States except US): **ABB AS**
[NO/NO]; Org. no 982 085 160, Billingstad (NO).

(72) Inventor; and

(75) Inventor/Applicant (for US only): **BRYNE, Gisle**
[NO/JP]; 2-52-17 Sangenjaya, Setagaya-Ku, Tokyo
154-0024 (JP).

(74) Common Representative: **ABB AS; c/o ABB AB, Legal
& Compliance/Intellectual Property, Forskargränd 8, S-721
78 Västerås (SE).**

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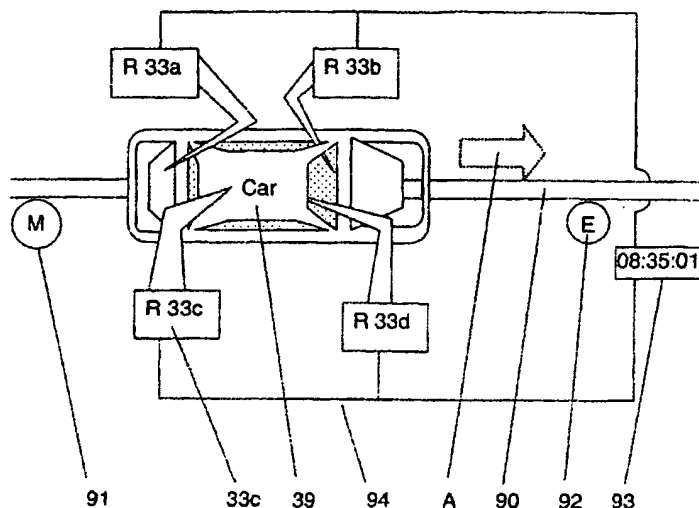
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(54) Title: CONTROL METHOD DEVICE AND SYSTEM FOR ROBOT APPLICATIONS



(57) Abstract: The invention is a method, controller and control system for controlling a robot that is used in concert with at least one other robot to perform an operation on one or more work objects. Each robot controller checks whether a common reference value is not acceptable, and if so, provides a signal for the robot to wait before proceeding to the next task. Each robot controller also checks whether the target object is in the correct position or not; and also checks whether or not another robot has stopped. If either another robot has stopped and/or if the work object is not in the right position, the robot waits. The invention is particularly advantageous for automated painting whereby a production line may be re-started more quickly again after a stoppage or production delay.

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